Privacy Preserving Image Registration

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Introduction

Image registration (IR) is the workhorse of many real-life medical imaging software and applications:

• Public web-based services for medical images segmentation [1];

• Federated Learning (FL) [2] where medical images can be jointly analyzed in multi-centric scenarios.





Problem



Medical imaging information falls within the realm of personal health data and its sensitive nature, these applications of image registration are no longer compliant with regulations currently existing in many countries, such as the GDPR [3], or HIPAA [4].



Contribution

We formulate the problem of **IR** under a privacy preserving regime, where **images** are assumed to be **confidential** and **cannot be disclosed in clear**.

Privacy Preserving Tools

Multi Party Computation (MPC)







Knows *x*

Knows y

Fully Homomorphic Encryption (FHE)





Background

We consider a scenario with two parties, $party_1$ and $party_2$, whereby owns $party_1$ image I and $party_2$ owns image J. The cost function to optimize the registration problem is the sum of squared intensity differences (SSD):

$$SSD(I, J, \mathbf{p}) = \arg\min_{\mathbf{p}} \sum_{\mathbf{x}} \left[I(W_{\mathbf{p}}(\mathbf{x})) - J(\mathbf{x}) \right]^{2}$$

Under Gauss-Netwon optimization scheme, the parameters of the spatial transformation can be computed as:

$$\Delta \mathbf{p} = \underbrace{H^{-1}}_{party_1} \cdot \sum_{\mathbf{x}} \underbrace{S(\mathbf{x})}_{party_1} \cdot \left(\underbrace{I(\mathbf{W}_{\mathbf{p}}(\mathbf{x}))}_{party_1} - \underbrace{J(\mathbf{x})}_{party_2} \right)$$

To compute the registration update the only operation requiring the joint availability of information from both parties is the term $R = \sum_{\mathbf{x}} \underbrace{S(\mathbf{x})}_{party_1} \cdot \underbrace{J(\mathbf{x})}_{party_2}$



Privacy Preserving Image Registration (PPIR)



Scalability of privacy preserving tools is achieved using gradient approximations, i.e. Uniformly Random Selection (URS) [5] and Gradient Magnitude Selection (GMS) [6].



Experimental Results

We demonstrate and assess **PPIR** based on **linear** (Figure 1, Table 1) and **non-linear registration**, by comparing the registration results with respect to the ones obtained with standard registration on clear images (Clear).

Affine registration metrics	5			
Solution	Intensity Error (SSD)	Num. Interation	Displacement RMSE CLEAR vs PPIR (mm)	
CLEAR	4.34 ± 0.0	118 ± 0.0	-	
SPDZ	4.34 ± 0.0	114.8 ± 4.0	1.81 ± 0.02	
CKKS	X	×	X	
CLEAR + URS	4.38 ± 0.0	61 ± 0.0	-	
SPDZ + URS	4.34 ± 0.0	60.4 ± 6.85	16.49 ± 3.74	
CKKS $(D = 128) + URS$	4.34 ± 0.10	61.80 ± 4.82	23.31 ± 2.72	
Clear + GMS	4.34 ± 0.0	63 ± 0.0	-	
SPDZ + GMS	4.34 ± 0.0	59.80 ± 6.20	6.21 ± 1.49	
CKKS $(D = 128) + GMS$	4.34 ± 0.05	60.4 ± 5.12	5.17 ± 1.40	
Affine efficiency metrics				
Solution	Time $party_1$ (s)	Time party ₂ (s)	Comm. party ₁ (MB)	Comm. party ₂ (MB)
CLEAR	0.0	0.0	-	-
SPDZ	0.13	0.13	1.54	1.54
CKKS	X	×	×	×
Clear + URS	0.0	0.0	-	-
SPDZ + URS	0.02	0.02	0.20	0.20
CKKS $(D = 128) + URS$	2.55	0.02	0.06	0.01
Clear + GMS	0.0	0.0	-	-
SPDZ + GMS	0.02	0.02	0.20	0.20
CKKS $(D = 128) + GMS$	2.51	0.02	0.06	0.01

Table 1: quantitative results for affine registration, where SPDZ = MPC and CKKS = FHE



Figure 1: qualitative results for affine registration

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Conclusion & Future Extensions

This work introduces **PPIR**, a novel framework to allow IR when **images** cannot be disclosed in clear. Future extensions are:

- Improve FHE time complexity;
- Apply to others cost function, i.e. Mutual Information

References

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Thanks!









